# Diameter-2-critical graphs with at most 13 nodes 

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#### Abstract

Diameter-2-critical graphs (abbr. D2C) are diameter 2 graphs whose diameter increases by removing any edge. The procedure used to obtain the list of D2C graphs of the order at most 13 is described. This is achieved by incorporating the diameter 2 test and the criticality test into geng, the program from the package nauty that generates the list of all non-isomorphic connected graphs. Experiments with the two heuristics in diameter 2 test, which is intensively used during the search, show that it is slightly more efficient to start the test with the largest degree node using BFS algorithm. As an application of the obtained list, the three conjectures concerning the maximum number of edges in D2C graphs were checked for graphs of the order at most 13 and one counterexample was found.


Index Terms: diameter-2-critical graphs, graph diameter, primitive graph.

## 1. Introduction

F $^{\text {OR }}$ an undirected graph $G=(V, E)$ (only undirected graphs are considered here) with the set of nodes $V$ and the set of edges $E$ let $\mathrm{d}_{G}(u, v)$ denote the distance between the nodes $u, v \in V$, i.e. the length of the shortest path connecting them. The order of $G$ is the number $|V|$ of its nodes. If from the context it is clear which graph is considered, the notation $\mathrm{d}(u, v)$ is used. Let $N_{k}(v)=\{u \mid \mathrm{d}(v, u) \leq k\}$ denote the (open) $k$-neighborhood of $v, N(v)=N_{1}(v)$, and let $N_{k}[v]=\{u \mid \mathrm{d}(v, u)=k\}$ be closed $k$ neighborhood. The diameter $\operatorname{diam}(G)$ of $G$ is the largest distance $\mathrm{d}(u, v)$ between any two distinct nodes $u, v \in V$. A graph $G=(V, E)$

[^0]is diameter- $k$-critical if $\operatorname{diam}(G)=k$, and for all edges $e \in E \operatorname{diam}(G \backslash e)>k$. The abbreviation D2C is used for diameter-2-critical graphs.

An isomorphism of two graphs $G=(V, E)$ and $H=(U, F)$ is a bijection $\phi: V \longrightarrow U$ such that $(u, v) \in E$ if and only if $(\phi(u), \phi(v)) \in F$. Two graphs $G$ and $H$ are isomorphic if there exists an isomorphism between them. An automorphism of a graph is any isomorphism of a graph to itself. The program geng [2] generates one graph for each class of mutually isomorphic undirected connected graphs, the canonical form of all graphs in the class [7].

D2C graphs are considered by many authors, see $[2 ; 3 ; 4]$ for example. There are many open problems related to them, see [5] for example. A possible approach to tackle open problems related to D2C graphs is the analysis of low order graphs. For this purpose, a list of all D2C graphs of order up to 13 was prepared.

So far, the most efficient method for generating a list of D2C graphs is to filter the list of non-equivalent connected undirected graphs obtained by the program geng. In the previous paper [10], similar work was done for D2C graphs of order up to 10 . The more efficient method used to obtain the list of all nonisomorphic D2C graphs of order up to 13 is described below. As far as the author is aware, there are no other published results of this type.

The rest of the paper is organized as follows. Section 2 describes two variants of the procedure used to generate D2C graphs using the program geng [2], modified by incorporating functions testing the diameter and the criticality. Section 3 presents some statistics concerning D2C graphs of order $n \leq 13$ and the results obtained by checking some conjectures about D2C graphs from [5]. Section 4 draws a

```
N2(A,n,v)
// A[n] - an integer array,
// the adjacency matrix
// of G=(V,E);
// n= |V|;
// v\inV - a starting node;
```



```
    N2v\leftarrow0
    for }i\leftarrow0\mathrm{ to }n-1\mathrm{ do
        if }\operatorname{Bit}(\mp@subsup{A}{v}{},i)=1 then
            N2v\leftarrowN2v|}\mp@subsup{A}{i}{
    return N2v
```

Figure 1: 2-neighborhood of $v, N 2(A, n, v)$.
conclusion based on the results.

## 2. Generation of D2C graphs

To generate canonical forms of all undirected graphs, a set of tools from the nauty package is used. This package also includes a program for reading and creating files containing listed graphs in supported formats [8]. Technical details about the integration of the diameter- 2 test and the criticality test into geng are given in the Appendix. Parallelization of the program is discussed in subsection 3.1.

### 2.1 Diameter-2 test

The diameter-2 test of $G=(V, E)$ consists of several runs of the simplified BFS algorithm (see [9], for example), which determines $N_{2}(v)$ by traversing $G$ starting from a given node $v \in V$, limiting the depth to 2 . Figure 1 shows the code of the algorithm. The adjacency matrix $A^{\prime}=\left[a_{i j}\right]$ of $G$, where $a_{i j}=1$ if $i j \in E$ and $a_{i j}=0$ otherwise, is represented by an integer array $A, A[i]=\sum_{j=1}^{|V|} a_{i j} 2^{|V|-j}$, coding the adjacency matrix rows. Here $\operatorname{Bit}(m, i)$ denotes the bit $i$ of the integer $m$. The returned integer $N 2 v=\bigvee_{w \in N(v)} A_{w}$ codes the set $N_{2}(v)$. The condition $N_{2}(v)=V$ is equivalent to $N 2 v=2^{n}-1$. The complexity of this test is $O(|V|)$.

The condition $\operatorname{diam}(G)=2$ is equivalent to $|E|<\binom{|V|}{2}$ and $N 2(A, n, v)=2^{n}-1$ for all $v \in V$. Diameter- 2 test can be improved by choosing some node $v \in V$ and checking first if $N_{2}(v)=V$ (see Figure 2), and then

```
\(i s d 2(A, n, m)\)
// \(A[n]\) - an array representing
// the adjacency matrix
// of \(G=(V, E)\);
// \(n=|V|\);
// \(m=|E|\);
// return true iff \(\operatorname{diam}(G)=2\).
    if \(m=\binom{n}{2}\) then return false
    choose a starting node \(v\)
    \(N 2 v \leftarrow N 2(A, n, v)\)
    if \(N 2 v<2^{n}-1\) then
        return false
    for \(w \leftarrow 0\) to \(n-1\) do
            if \(\operatorname{Bit}(N 2 v, w)=1\) and
                \(N 2(A, n, w)<2^{n}-1\) then
                return false
    return true
```

Figure 2: The diameter 2 test $i s d 2(A, n, m)$.

- if this condition is not satisfied, then $\operatorname{diam}(G)>2$;
- otherwise check if $N_{2}(w)=V$ only for all $w \in N_{2}[v]$ (if $r, s \in N_{1}[v]$, then $\mathrm{d}(r, s) \leq$ 2 because both $r$ and $s$ are connected with $v$ ).

The complexity of this check is $O(|V|$. $\left.\left|N_{2}[v]\right|\right)$, suggesting the two different heuristics, controlling choice of the starting node $v$ :

- $\mathrm{H} 1: v$ is one of the largest degree nodes;
- H2: $v$ is one of the smallest degree nodes.

If there are several nodes with the smallest or the largest degree in $G$, the first such node in the canonical form of $G$ is taken.

The advantage of H 1 is that it minimizes the number of calls to $N 2(A, n, w)$. On the other side, if $\operatorname{diam}(G)>2$, then H 2 is expected to increase the probability of detecting that $\operatorname{diam}(G)>2$ after the first test $N 2(A, n, v)=$ $2^{n}-1$ applied to starting node $v$, thus eliminating all the remaining tests $N 2(A, n, w)=$ $2^{n}-1$. Overall complexity of the diameter-2 test is $O\left(|V|^{2}\right)$, because

- if $N_{2}(v) \neq V$, then the complexity is $O(|V|)$;
- otherwise if $N_{2}(v)=V$, then the complexity is $O\left(|V|\left|N_{2}(v)\right|\right)$.

```
isd2c(A,n,m)
// A[n] - an array representing
// the adjacency matrix
// of G=(V,E);
// n= |V|;
// m= |E|;
// return true iff G is D2C.
if not isd2(A,n,m) then
    return false
for }u\leftarrow0\mathrm{ to }n-2 d
    for }v\leftarrowu+1 to n-1 d
        if }\mp@subsup{\operatorname{Bit}}{v}{}(\mp@subsup{A}{u}{})\not=
        and }\mp@subsup{A}{u}{&}\mp@subsup{A}{v}{}\not=0\mathrm{ then
            A'}\leftarrow\mathrm{ array of }G\(u,v
            if not isd2( }\mp@subsup{A}{}{\prime},n,m-1) the
                return false
return true
```

Figure 3: D2C test $\operatorname{isd} 2 c(A, n, m)$.

### 2.2 The criticality test

Checking the diameter-2-criticality of a graph is performed only for graphs $G$ such that $\operatorname{diam}(G)=2$. Let $A$ denote the integer array coding the rows of the adjacency matrix of $G$. In terms of used coding, an edge $(u, v) \in E$ is triangular if and only if $A_{u} \wedge A_{v} \neq 0$. The improved criticality test of $G$ is based on the fact that it is sufficient to check the condition $\operatorname{diam}(G \backslash(u, w))>2$ only for triangular edges $(u, w) \in E$, see the code $\operatorname{isd} 2 c(A, n, m)$ in Figure 3. The complexity of $\operatorname{isd} 2 c(A, n, m)$ is $O\left(|E||V|^{2}\right)=O\left(|V|^{4}\right)$.

## 3. Results

The results of the two heuristics comparison are given in subsection 3.1. Some statistics concerning D2 (for $n \leq 12$ ) and D2C graphs (for $n \leq 13$ ) are listed in subsection 3.2. The results of testing some conjectures concerning D2C graphs are given in subsection 3.3.

### 3.1 The efficiency evaluation

Experiments are conducted in order to compare the two heuristics H 1 and H 2 . The program is run on a computer with the processor AMD Ryzen 74800 H with 8 cores and 16.0 GB RAM at 2.90 GHz using Ubuntu.

All the nonequivalent connected graphs are
divided into the following classes in isd2 function:

- CO: all the connected graphs;
- C1: the graphs $G$ with $N_{2}(v) \neq V$ (implying $\operatorname{diam}(G)>2$ ), where $v$ is the chosen starting node;
- C2: the graphs $G$ with $N_{2}(v)=V$ and $\operatorname{diam}(G)>2$ or $\operatorname{diam}(G)=1$, and
- D2: the graphs $G$ with $\operatorname{diam}(G)=2$.

For both heuristics $|C 1|+|C 2|=|C 0|-|D 2|$ holds.

As the program geng generates graphs of the given order $n$ and with the given number $m$ of edges, in a parallel version of the program processors independently generate the lists of graphs obtained for various $m$.

The complete lists of D2C graphs of the order up to 11 are obtained in a short time, even without parallelization. For the graphs of the order 12 and 13 the modified version of geng is run in parallel. The times in seconds required to obtain all the graphs of diameter 2 of orders less than 13 are shown in Table 1. To obtain the list of D2C graphs of order 13, the parallel execution takes more than a month.

|  | Sequential |  | Parallel |  |
| ---: | ---: | ---: | ---: | ---: |
| $n$ | H 1 | H 2 | H 1 | H 2 |
| 9 | 0.1 | 0.1 |  |  |
| 10 | 2.9 | 3.2 | 0.6 | 0.7 |
| 11 | 278.8 | 303.9 | 41.3 | 44.6 |
| 12 | 43717.7 | 47796.0 | 6147.8 | 6839.0 |

Table 1: Execution times of sequential and parallel program versions.

The efficiency of a such parallelization is constrained by the fact that the number of graphs in D2 follow approximately the binomial distribution in terms of the number $m$ of edges. The time required to check all the graphs in C0 with $n=12$ and $m=33=\frac{1}{2} n(n-1) / 2$ for $\mathrm{H} 1, \mathrm{H} 2$ is $4136.21 s, 4552.41 s$ respectively, while the total time (for all the graphs in C0) is $43717.69 \mathrm{~s}, 47796.05 \mathrm{~s}$ respectively. As the heuristic H 1 proved to be more efficient, it was the only heuristic used for graphs of order 13.

### 3.2 Some statistics concerning small D2C graphs

The numbers of D2 and D2C graphs are listed in Table 2. As it can be seen, the number of D2 graphs of the order $n \leq 12$ is much larger than the number of D2C graphs. The huge number of D2 graphs of the order 13 were not collected during the one-month program run.

| $n$ | $\|D 2\|$ | $\|D 2 C\|$ |
| ---: | ---: | ---: |
| 3 | 1 | 1 |
| 4 | 4 | 2 |
| 5 | 14 | 3 |
| 6 | 59 | 5 |
| 7 | 373 | 10 |
| 8 | 4154 | 30 |
| 9 | 91518 | 103 |
| 10 | 4116896 | 519 |
| 11 | 369315249 | 3746 |
| 12 | 64093257952 | 40866 |
| 13 |  | 688118 |

Table 2: The numbers of D2 and D2C graphs.
The diagram in Figure 4 shows the dependence of $|D 2| /|D 0|$ and $\log _{10}(|D 2 C| /|D 2|)$ on $n$. It is well known [1] that for the large order $n$ almost all graphs have diameter 2. Figure 4 shows that the number of diameter-2 graphs is above $1 / 3$ of the number of all connected graphs for $n \leq 12$. On the other side, the ratio $|D 2 C| /|D 2|$ rapidly diminishes in this range.

The minimum and the maximum number of edges in graphs of diameter 2 are extensively studied. A graph is primitive if there are no two nodes with the same neighborhood. Table 3 shows the minimum and the maximum number of edges in D2C and PD2C (primitive D2C) graphs of order up to 13 . Minimal D2C graphs are the stars $S_{n}$ (the graphs of order $n$ with the $n-1$ edges connecting one node with all the other nodes) and only they reach the lower bound on the number of edges.


Figure 4: The dependence of $|D 2| /|D 0|$ and $\log _{10}(|D 2 C| /|D 2|)$ on $n \leq 12$.

### 3.3 Checking conjectures about D2C graphs

The obtained list of D2C graphs is used to check some conjectures about these graphs for $n \leq 13$ [5].

Plesnik [3] and Murty and Simon [2] independently stated the following conjecture.

Conjecture 1 A D2C graph of order $n$ has at most $\left\lfloor\frac{n^{2}}{4}\right\rfloor$ edges, with the equality if and only if $G$ is a balanced complete bipartite graph.

Fan [6] proved Conjecture 1 for $n \leq 24$. This result is partially verified for $n \leq 13$.

A dominating edge in a graph connects a pair of adjacent nodes that have no common non-neighbour. Denote by $C_{5}^{+}$[4] the family of "expanded 5 -cycles", i.e. graphs obtained by replacing three nodes $x_{1}, x_{2}, x_{3}$ of a 5 -cycle by three independent sets $X_{1}, X_{2}, X_{3}$ of nodes, under the following conditions: (1) $x_{1}, x_{2}$ and $x_{3}$ are consecutive on the 5-cycle; (2) $\left|X_{2}\right| \in$ $\left\{\left\lfloor\frac{n-2}{3}\right\rfloor,\left\lceil\frac{n-2}{3}\right\rceil\right\}$, where $n$ is the order of the obtained graph. Dailly [5] stated the following conjecture.

Conjecture 2 Let $G$ be a non-bipartite D2C graph without a dominating edge. Then $G$ has at most $\left\lfloor\frac{(n-1)^{2}}{4}\right\rfloor+1$ edges. For sufficiently large $n$, the equality holds if and only if $G$ belongs to $C_{5}^{+}$.

The check of conjecture shows that there are no counterexamples for $n \leq 13$.

| $n$ | Min $m$ <br> D2C | Min $m$ <br> PD2C | Max $m$ <br> PD2C | Max $m$ <br> D2C |
| ---: | ---: | ---: | ---: | ---: |
| 3 | 2 |  |  | 2 |
| 4 | 3 |  |  | 4 |
| 5 | 4 | 5 | 5 | 6 |
| 6 | 5 | 8 | 8 | 9 |
| 7 | 6 | 9 | 10 | 12 |
| 8 | 7 | 12 | 13 | 16 |
| 9 | 8 | 14 | 17 | 20 |
| 10 | 9 | 15 | 20 | 25 |
| 11 | 10 | 18 | 24 | 30 |
| 12 | 11 | 20 | 32 | 36 |
| 13 | 12 | 22 | 36 | 37 |

Table 3: Maximal and minimal number of edges in D2C and PD2C graphs of order up to 13.

Conjecture 3 Let $G$ be a non-bipartite D2C graph of order n. If $G$ is not $H_{5}$ [5, Figure 2], then $G$ has at most $\left\lfloor\frac{(n-1)^{2}}{4}\right\rfloor+1$ edges, with the equality if and only if $G$ belongs to $C_{5}^{+}$or it is one of the thirteen graphs of order $n \leq 11$ listed in [5, Figure 3].

The list of exceptions is verified for $n \leq 11$, and the new exception is found, the graph of order 12 with the 32 edges, see Figure 5; here $32>\left\lfloor\frac{(n-1)^{2}}{4}\right\rfloor+1=31$. The graph contains a dominating edge, which is colored red. The number of edges of this graph appears as the extreme value in Table 3. There are no exceptions of order 13 to Conjecture 3.

## 4. Conclusion

The list of all D2C graphs of order $n \leq 13$, and the list of all diameter-2 graphs of order $n \leq 12$ are obtained. Two heuristics for diameter- 2 testing, concerning the choice of the starting node, were compared. It appears that the choice of the largest degree node as a starting node is slightly more efficient, at least for $n \leq 12$. Using the list of D2C graphs, the three conjectures are checked for $n \leq 13$. The graph of order 12 is found, which is a new exception to Conjecture 3. An interesting question


Figure 5: The graph that is a counterexample to Conjecture 3.
is whether the advantage of heuristics H 1 also applies to graphs of order greater than 12. Another question is whether more efficient heuristics can be found, which could increase the limit on the order of generated D2C graphs.

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## Appendix: integration of the tests INTO geng

The geng program (written in $C$ ) is a part of the nauty package, used to list all nonisomorphic connected graphs that have a given number of nodes and edges [8]. The listed graphs are in graph6 format, which is supported by the program itself. Here the modification of geng used to obtain the list of D2C graphs, that have a given number of nodes and edges, is described.

If the argument $-c$ is passed with the graph order $n$ in the call of geng, only connected graphs of the order $n$ are generated. When the
main function of geng receives the argument $-c$, the variable connec 1 becomes TRUE and the global variable connec becomes 1. To generate graphs, the recursive function genextend is called. In the function genextend the global variable connec forces the filtering of connected graphs by calling the function isconnected.

In a similar way, the function $i s d 2 c$ implementing criticality test $i s d 2 c$ is incorporated. In the main function a check is added if there is an argument $-k$ in the program call, indicating that the criticality of graphs should be checked. The new global variable $d 2 c$ is used to store the $-k$ argument and to force the genextend function to call the function isd2c.

The function $i s d 2 c$, implementing the algorithm $i s d 2 c$ above, accepts as arguments graph ${ }^{*} g$, the graph, int $n$, the order of $g$, and int $m$, the number of edges in $g$. The type graph is defined in the package nauty and is used to represent the graph as an integer sequence (the array $A$ in the call to $i s d 2 c$ ). In the function $i s d 2 c$ for each triangular edge $e \in E$ the condition $\operatorname{diam}(G \backslash e)=2$ is checked, by calling the function $i s d 2$.


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